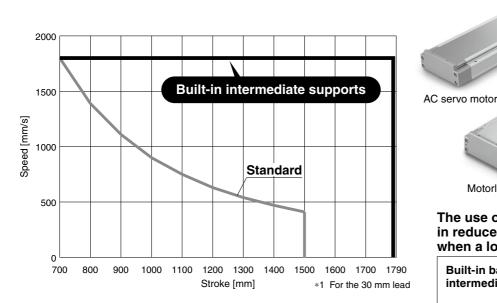
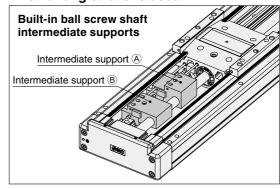
# Built-in Intermediate Supports (AC Servo Motor)

# **Electric Actuator: High Rigidity Slider Type Ball Screw Drive**

■A maximum speed of 1,800 mm/s\*1 has been achieved throughout the entire stroke!



Motorless type The use of intermediate supports results in reduced deflection of the ball screw when a long stroke is used.



- Max. stroke: 1,790 mm
- Horizontal work load: 85 kg (For the 10 mm lead)
- Positioning repeatability:
  - $\pm 0.01$  mm (High-precision type)

#### **AC Servo Motor**

#### For absolute encoders

- Pulse input type LECSB Series
- CC-Link direct input type LECSC Series
- SSCNETⅢ type LECSS Series
- SSCNETⅢ/H type LECSS-T Series
- MECHATROLINK type LECY□ Series









## For incremental encoders

Pulse input type/ Positioning type LECSA Serie



## Motorless Manufacturers of compatible motors: 13 companies

- Mitsubishi Electric Corporation
  YASKAWA Electric Corporation
  SANYO DENKI CO., LTD.
  OMRON Corporation
  Panasonic Corporation
- FANUC CORPORATION NIDEC SANKYO CORPORATION KEYENCE CORPORATION FUJI ELECTRIC CO., LTD.
- Rockwell Automation, Inc. (Allen-Bradley) Beckhoff Automation GmbH Siemens AG Delta Electronics, Inc.



Built-in Intermediate Supports These specifications enable the maximum speed to be realized throughout the entire stroke.

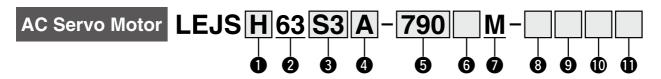
# **Electric Actuator: High Rigidity Slider Type**

**Ball Screw Drive** 

LEJS63□-□M Series ■



### **How to Order**



Accuracy

Hooditaby		
Nil	Basic type	
Н	High-precision type	

2 Size 63

**3** Motor type

	Symbol	Туре	Output [W]	Actuator size	Compatible driver
	S3	AC servo motor (Incremental encoder)	200	63	LECSA□-S3
	<b>S</b> 7	AC servo motor (Absolute encoder)	200	63	LECSB□-S7 LECSC□-S7 LECSS□-S7
	Т7	AC servo motor (Absolute encoder)	200	63	LECSS2-T7
	V7	AC servo motor (Absolute encoder)	200	63	LECYM2-V7 LECYU2-V7

4 Lead [mm]

Н	30
Α	20
В	10

5 Stroke [mm]*1		n]*1	Standard C	Produced upon	receipt of order
790	890	990	1190	1490	1790

Please consult with SMC for non-standard strokes as they are produced as special orders.

$\mathbf{\Theta}$	Motor	option

Nil	None
В	With lock

## Built-in intermediate supports Built-in intermediate supports

#### 8 Cable type\*2 \*3

Nil	Without cable
S	Standard cable
R	Robotic cable (Flexible cable)

\*2 When a driver type is selected, a cable is included. Select the cable type and cable length.

Example)

S2S2: Standard cable (2 m) + Driver (LECSS2)

Standard cable (2 m) Without cable and driver

\*3 The motor and encoder cables are included. (The lock cable is included when the motor with lock option is selected.)

# Cable length\*2 \*4

NI:I	Nil Without cable		r type
IVII	williout cable	S□/T□	V
2	2	•	_
3	3	_	•
5	5	•	•
Α	10	•	•
С	20	_	•

<sup>\*4</sup> The length of the motor, encoder, and lock cables are the same.

## Driver type\*2

Symbol	Compatible driver	Power supply voltage [V
Nil	Without driver	_
A1	LECSA1-S□	100 to 120
A2	LECSA2-S□	200 to 230
B1	LECSB1-S□	100 to 120
B2	LECSB2-S□	200 to 230
C1	LECSC1-S□	100 to 120
C2	LECSC2-S□	200 to 230
S1	LECSS1-S□	100 to 120
S2	LECSS2-S□	200 to 230
32	LECSS2-T□	200 to 240
M2	LECYM2-V□	200 to 230
U2	LECYU2-V□	200 to 230

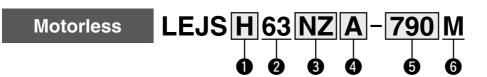
#### I/O connector\*5

1

Nil	Without cable
Н	Without cable (Connector only)
1	1.5 [m]

<sup>\*5</sup> When "Without driver" is selected, only "Without cable" can be selected.

## **How to Order**



## Accuracy

	Nil	Basic type
	Н	High-precision type



## **3** Motor type

NZ	Mounting type Z
NY	Mounting type Y
NX	Mounting type X
NW	Mounting type W
NV	Mounting type V
NU	Mounting type U
NT	Mounting type T
•	

## 4 Lead [mm]

Н	30
Α	20
В	10

<b>6</b> Stro	ke [mr	n]*1 <b>(</b>	Standard O	Produced upon	receipt of order
790	890	990	1190	1490	1790
•	•	0	0	0	0

## 6 Built-in intermediate supports Built-in intermediate supports

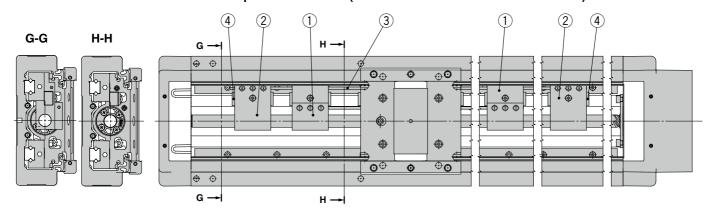
## **Specifications**

	Lead [mm]	30	20	10	
Work load [kg]	Horizonta		30	45	85
work load [kg]	Vertical	6	10	20	
		790			600
		890		1200	
Cnood [mm/o]	Ctuaka sanga	990	1800		
Speed [mm/s]	Stroke range	1190	1000		
		1490			
		1790			

Other specifications that are not listed are the same as those of the standard product. For details, refer to the Web Catalog.

## Construction

#### Top view of actuator (Shown with the dust seal band removed)



#### **Component Parts**

No.	Description	Material
1	Support A	Synthetic resin
2	Support B	Synthetic resin
3	Connection pipe	Stainless steel
4	Bumper	Low-elasticity rubber

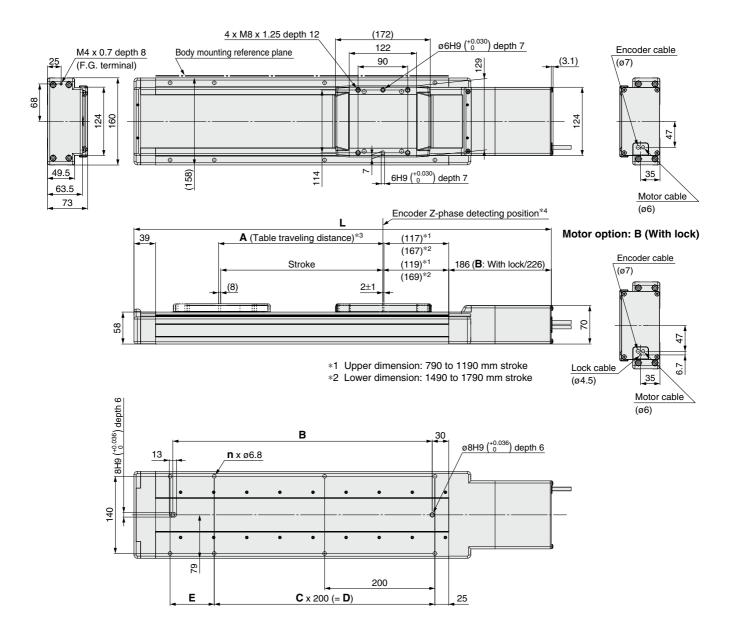


<sup>\*1</sup> Please consult with SMC for non-standard strokes as they are produced as special orders.

# LEJS63□-□M Series

## **Dimensions: Ball Screw Drive**

#### AC servo motor



- \*3 This is the distance within which the table can move when it returns to origin. Make sure workpieces mounted on the table do not interfere with the workpieces and facilities around the table.
- \*4 The Z-phase first detecting position from the stroke end of the motor side
- \* The auto switch magnet is located in the table center.

Dimensions and Weight [mm]									
Model	L		Α	В	n	С	D	Е	Product weight*1
Model	Without lock	With lock	_ ^	-				_	[kg]
LEJS□63□□-790□M-□□□□	1256.5	1296.5	800	970	12	4	800	180	19.4
LEJS□63□□-890□M-□□□□	1356.5	1396.5	900	1070	14	5	1000	80	20.7
LEJS□63□□-990□M-□□□□	1456.5	1496.5	1000	1170	14	5	1000	180	21.9
LEJS□63□□-1190□M-□□□□	1656.5	1696.5	1200	1370	16	6	1200	180	24.4
LEJS□63□□-1490□M-□□□□	2056.5	2096.5	1500	1770	20	8	1600	180	29.9
LEJS□63□□-1790□M-□□□□	2356.5	2396.5	1800	2070	24	10	2000	80	33.7

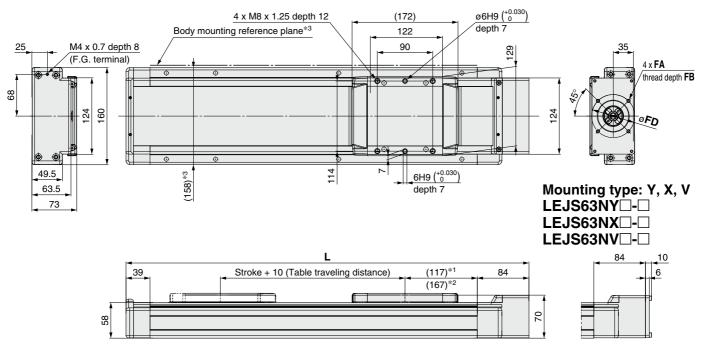
<sup>\*1</sup> When using a lock, add 0.4 (incremental encoder) or 0.7 (absolute encoder).



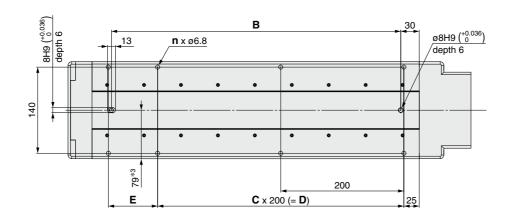
Refer to the "Motor Mounting" on page 5 for details about motor mounting and included parts.

## **Dimensions: Ball Screw Drive**

#### **Motorless**



\*1 Upper dimension: 790 to 1190 mm stroke \*2 Lower dimension: 1490 to 1790 mm stroke



\*3 When mounting the actuator using the body mounting reference plane, use a pin. Set the height of the pin to be 5 mm or more because of round chamfering. (Recommended height 6 mm)

Dimensions and Weight [mm]							
Model	L	В	n	С	D	E	Product weight [kg]
LEJS□63N□□-790M	1154.5	970	12	4	800	180	18.4
LEJS□63N□□-890M	1254.5	1070	14	5	1000	80	19.7
LEJS□63N□□-990M	1354.5	1170	14	5	1000	180	20.9
LEJS□63N□□-1190M	1554.5	1370	16	6	1200	180	23.4
LEJS□63N□□-1490M	1954.5	1770	20	8	1600	180	28.9
LEJS□63N□□-1790M	2254.5	2070	24	10	2000	80	32.7

Motor Mounting Dimensions [mm]					
Motor type	FA	FB	FD		
NZ/Mounting type Z	M5 x 0.8	7	70		
NY/Mounting type Y	M4 x 0.7	6	70		
NX/Mounting type X	M5 x 0.8	6	63		
NW/Mounting type W	M5 x 0.8	7	70		
NV/Mounting type V	M4 x 0.7	6	63		
NU/Mounting type U	M5 x 0.8	7	70		
NT/Mounting type T	M5 x 0.8	7	70		

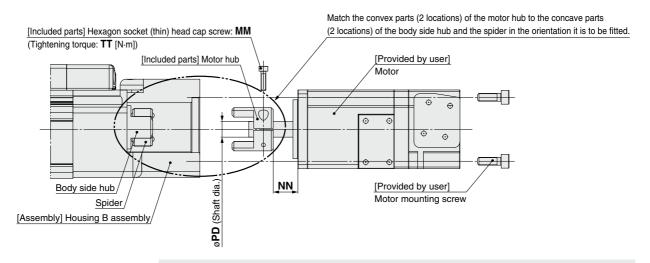


## LEJS63□-□M Series

#### • When mounting a hub, remove all oil content, dust, and dirt adhered to the shaft and the inside of the hub.

- This product does not include the motor and motor mounting screws. (Provided by user)
  Prepare a motor with a round shaft end.
- Take measures to prevent the loosening of the motor mounting screws.

## **Motor Mounting**



#### **Mounting procedure**

- 1) Secure the motor hub to the motor (provided by user) with the MM hexagon socket head cap screw.
- 2) Check the motor hub position, and then insert it.
- 3) Secure the motor to the housing B assembly with the motor mounting screws (provided by user).

Dilliel	1310113				[mm]
Size	Motor type	MM	TT	NN	PD
	NZ/Mounting type Z	M3 x 12	1.5	18	14
	NY/Mounting type Y	M4 x 12	2.7	18	11
	NX/Mounting type X	M4 x 12	2.7	8	9
63	NW/Mounting type W	M4 x 12	2.7	12	9
	NV/Mounting type V	M4 x 12	2.7	8	9
	NU/Mounting type U	M4 x 12	2.7	12	11
	NT/Mounting type T	M3 x 12	1.5	18	12

### **Included Parts List**

#### Size: 63

Description	Qty.	Note			
Motor hub	1				
Hexagon socket head cap screw (to secure the hub)	4	M3 x 12: Motor type NZ, NT			
Hexagon socket thin head cap screw (to secure the hub)	<b>I</b>	M4 x 12: Motor type NY, NX, NW, NV, NU			

### **⚠** Caution

Dimensions

- 1. During operation, the intermediate support mechanism emits a collision noise due to the structure.
- 2. Compared to the standard product, the entire length of the product will be longer for each stroke. For details, refer to the dimensions.
- 3. The stopper type origin position return method cannot be used as the return to origin method (due to the bumper as shown in Construction ④).

▲ Safety Instructions | Be sure to read the "Handling Precautions for SMC Products" (M-E03-3) and "Operation Manual" before use.



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